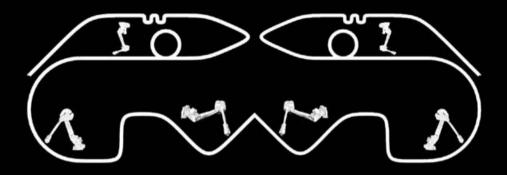
## Modeling and Control of Flexible Manipulators

Stig Moberg





Linköping 2010

